

MINGXUAN LI

Columbia University, New York, NY 10027
(401)225-6526 ◊ ml@cs.columbia.edu ◊ https://mingxuan.me

EDUCATION

- Columbia University** *Sept 2021 - Now*
PhD in Computer Science (Causal Inference & Reinforcement learning)
- Brown University** *Sept 2019 - June 2021*
ScM in Computer Science, GPA: 4.0/4.0
Selected Courses: Learning and Sequential Decision Making (A), Introduction to Robotics (A),
Reintegrating AI (A)
- Hong Kong University of Science and Technology (HKUST)** *Feb 2018 - June 2018*
Exchange Student in Computer Science; Major GPA: 4.0/4.3
Selected Courses: Intro to Bayesian Networks (A-), Data Visualisation (A+)
- Beihang University** *Sept 2015 - June 2019*
B.S in Computer Science and Technology; Overall GPA: 3.7/4.0
Selected Courses: Compiler Theory (97/100), Image Processing and Pattern Recognition (100/100),
Introduction to Machine Learning (100/100)

RESEARCH INTERESTS

Causal Inference, Reinforcement Learning, Adversarial Robustness

PUBLICATIONS

- “Towards Sample Efficient Agents through Algorithmic Alignment” - *AAAI 21 Student Abstract and Poster Program (Accepted)* **Mingxuan Li**, Michael L. Littman
- “Interpretability is a Kind of Safety: An Interpreter-based Ensemble for Adversary Defense” - *KDD 2020 (Accepted)* Jingyuan Wang, Yufan Wu, **Mingxuan Li**, Xin Lin, Junjie Wu, Chao Li
- “Replication of ‘When to Trust Your Model: Model-Based Policy Optimization’ ” - *Preprint* **Mingxuan Li***, Xiaoyu Jiang*, Qiuxuan Chen*, Shiyi Han*, Jingyan Dong*, Ruo Chen Zhang*
- “Are L2 adversarial examples intrinsically different?” - *Preprint* **Mingxuan Li**, Jingyuan Wang, Yufan Wu

SELECTED RESEARCH EXPERIENCE

- Learning to Control with the Explainable Latent Dynamics Graph** Jan. 2021 - Sept. 2021
Advisor: Prof. Michael L. Littman *RLab, Brown University*
- Lead the effort to build a generalizable StarCraft agent for DARPA XAI project;
 - Designed the Latent Local Planning Network, an explainable world model that explicitly learns the latent dynamics purely from pixel inputs without reconstruction;
 - Proposed soft lambda return actor-critic learning behaviours from pure simulated trajectories;
- Towards Sample Efficient Agents through Algorithmic Alignment** Mar. 2020 - May 2020
Advisor: Prof. Michael L. Littman *RLab, Brown University*
- Revealed the potential of GNNs in sample efficient learning by creating the Deep Graph Value Networks (DeepGVs);
 - DeepGVs efficiently solved MDPs and outperformed unstructured baseline by over 50%;

- Resulted in an abstract paper accepted by AAAI-21 Student Abstract and Poster Program.

Robust Adversaries Detection and Recovery

Mar. 2019 - Nov. 2019

Advisor: Prof. Jingyuan Wang, Dr. Shuchang Zhou

Megvii CV Group, Beihang U

- Was a key player in designing an input sensitivity based adversarial examples detection and recovery pipeline which achieved an average of 96% detection accuracy and high robust classification accuracy against famous adversaries;
- Developed a theoretical explanation of L_2 adversarial examples' intrinsic properties that can differentiate them from normal inputs;
- Formed two research papers as first author and second student author, respectively, one of which is accepted by KDD 2020.

INTERNSHIP EXPERIENCE

Turing Microbe Co.,Ltd

Mar. 2019 - Jul. 2019

Advisor: Prof. Wei Xu(IIS, Tsinghua U)

Computer Vision Research Intern, R&D Department

- Analysed over 30,000 cases of gynaecological diseases data with T-SNE and deep clustering to give doctors insights on new taxonomy for Bacterial Vaginal(BV) diagnosis;
- Used StyleGAN to generate realistic and highly diverse BV pictures for training young doctors;
- Highly recognized by Prof. Qinqing Liao, the chairman of the Chinese Medical Doctor Association, the gynaecology branch, for insightful data analysis and practical application value of the work.

SELECTED PROJECTS

PiDrone: An autonomous drone using Raspberry Pi

Sept. 2019 - Dec. 2019

Course Project

Brown University

- Built a drone equipped with Raspberry Pi from scratch under the guidance of online manuals;
- Implemented core algorithms to enable the drone to fly, including PID controller, speed control with optical flow, state estimation with unscented Kalman Filter and position control with SLAM;
- Got a solid grasp of foundations of robotics and probabilistic control theory.

JPEG-2000 Standard Image I/O Pipeline

May 2019 - Jun. 2019

Personal Side Project

Beihang U

- Implemented 2D-FastDCT and 2D-FFT in JAVA;
- Analysed JPEG-2000 ISO standard and implemented the whole I/O process including image header information extraction without using any external JAVA image processing packages;
- Provided a visual interface for previewing the processed image along with its grey scale distribution.

AWARDS&HONOURS

10/2018, Scholarship for Academic Achievements, Second Prize (Top 10%)

09/2018, Was selected to appear on the Deans List for the School of Engineering, HKUST

09/2017, The 1st National Student Computer System Capability Challenge, Second Prize (Final 2/70)

05/2017, The 27th "FengRu Cup" University Students Extra-Curricular Scientific and Technological Invention Competition, Second Prize (Final 4/176)